## Class 18 (Week 9, T) Induction I: constraints

#### To do

- □ Work on your project! (There's no more homework and no more reading.)
- □ There is no class on Thursday (Thanksgiving)
- □ Next Tuesday we meet **4-6 PM**, in **Campbell 2122** (conference room)

**Overview**: What if we aren't born with a constraint inventory? We'll take a tour of some proposals.

## 1. Discuss Hayes & Wilson (2006)

## 2. Naradowsky, Pater & Smith (2011): Error-driven constraint induction

- Do we really need to consider such a broad range of constraints?
- Main idea:

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- When you hear a form (say, [#n...]), compare it to a randomly sampled, hypothetical similar form (e.g., [#ŋ...])
- If your current grammar assigns better harmony to the sampled neighbor than to the observed form, the grammar needs updating
  - Can you see a problem with this?
  - Refinement: remember the last *n* forms you heard (here, *n*=3000), and don't worry about a neigbor that's in that set
- How to construct a constraint
  - Make a lattice of all the constraints that could prefer the observed form
    - In the [#n...]/[#n...] example, consider all constraints that penalize [+dorsal]
      - In the feature system used in this paper, [CORONAL] is privative
      - Which means what?
      - Let's draw some of the lattice.

- Sample a few of these constraints (here, 3) and add them to the grammar
- Update weights of this new constraint set
  - Use Perceptron rule to update: similar to Gradual Learning Algorithm, except it cares about the number of violations
- More precisely: see over

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Algorithm 1 Learning Procedure
 1: function LEARN
        model \leftarrow []
 2:
        while learning do
 3:
            o \leftarrow draw(D)
 4:
            u \leftarrow draw(neighborhood(o))
 5:
            if model.score(u) > model.score(o) then
 6:
                                                                     ▷ Constraint Induction
                diff \leftarrow u.features \setminus o.features
 7:
                cspace \leftarrow []
 8:
                for c \leftarrow all constraints do
                                                                                ▷ Filter Space
 9:
                    if c.contains(diff) then
10:
                        cspace + = c
11:
                    end if
12:
                    model. features + = draw(space)
                                                                            ▷ Add constraint
13:
14:
                end for
                for j \leftarrow 0 until model.size do
                                                                        \triangleright Perceptron Update
15:
                    model[j] = f.violations(u) - f.violations(o) * rate
16:
                end for
17:
            end if
18:
        end while
19:
20: end function
21:
22: function NEIGHBORHOOD(o)
        plattice \leftarrow [o.size]
23:
        for i \leftarrow o.size do
24:
            plattice[i] \leftarrow o[i].phones
                                                                  \triangleright (Phone, Distance) pairs
25:
        end for
26:
27:
        return draw(plattice.allPaths)
                                                                 \triangleright Sum weight in each path
28: end function
```

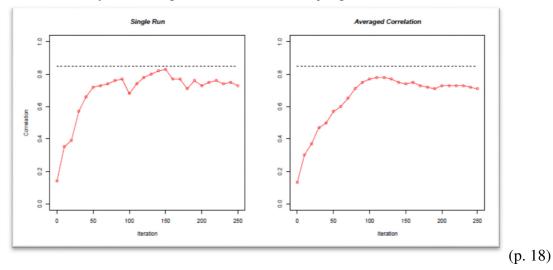
- Tested on English onsets, as in Hayes & Wilson (2006)
- Resulting constraints (over):
  - [\_] means "any segment", i.e. [+segmental]

(p. 13)

Weight	Feature	Description
1.34	[_] [^-strid,+cor]	S T vs. TH S
1.28	[^+cons,+ant]	S vs ZH
1.26	[^-approx,+lab]	M vs. NG
1.26	[_] [^-cons,+cor]	G R vs. P W
1.26	[-approx,-voice] [^-ant,+cor]	G R vs. CH L
1.22	[^-son,-voice] [_]	S K vs. Z P
1.22	[^+strid][-strid,+son]	S L vs TH L
1.20	[^-son,+voice][+lab]	G R vs. P W
1.20	$[^+dorsal,+cons][^+approx,-ant]$	G R vs. P W
1.20	[^+dorsal][^-strid,-ant]	G R vs. CH L
1.18	[^+cont,-voice]	S vs. ZH
1.18	[+strid,+cor][^-strid]	S T vs. S S
1.18	[-son,-voice][_]	G R vs. P W
1.18	[_][^+approx,+cor]	G R vs. P Y
1.16	[-son,+ant][-ant]	S W vs. S R
1.16	[_][^+high,+approx]	S W vs. S R
1.16	[_][^+high,+son]	S W vs. S R
1.16	[^-voice][_]	T R vs. V R
1.14	[^+strid,-voice][_]	S L vs. TH L
1.14	$[-son][^+ant,+lat]$	S L vs. S R

(p. 16)

- Correlation to human judgments of English onsets: -0.829 (vs. Hayes & Wilson's -0.859)
- Interesting problem: tendency towards over-fitting as learning continues
  - As assessed by worsening correlation to human judgments

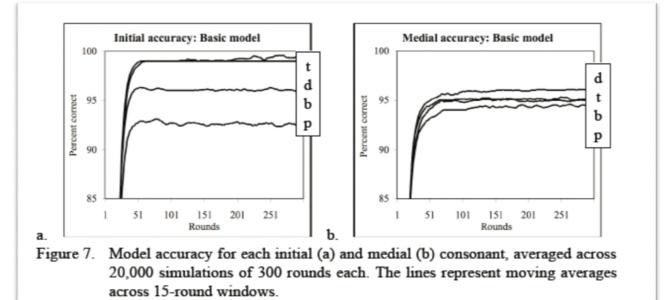


Ling 219, Phonological Theory III. Fall 2015, Zuraw

- See the paper for some ways to improve the model
- Discuss: Both this model and the Hayes/Wilson model are for phonotactic learning. How could we extend either of these to learning alternations?
- **3.** Flack (2007): inducing a constraint from perceptual experience

We got this far.

- There are languages that prohibit [p] specifically in word-initial position: \*#P
  - Initial [p] has particularly short VOT, and it's more variable than initial [b]'s
  - Difference in maximum burst intensity for initial [p] and [b] is smaller than for other voiceless-voiced pairs (p. 122)
- To produce an instance of a category ([p], [b], [t], etc.) in a context, speaker samples values for various phonetic dimensions from stored distributions centered on prototype
- In perception, listener must guess the category
  - Some noise is added: perception is imperfect
  - Rather than Bayes' rule as in Kirby (2013), finds the closest prototype
- Listener gets feedback on accuracy
  - Allows listener to update prototypes
  - Listener also stores accuracy rate for each category, perhaps over a moving window of the past *n* tokens (here, *n*=400)
    - Specifically, **hit rate** and **false alarm rate**
    - Does anyone know these terms?
- Hit rates for each consonant as learning proceeds over time:



(p. 141)

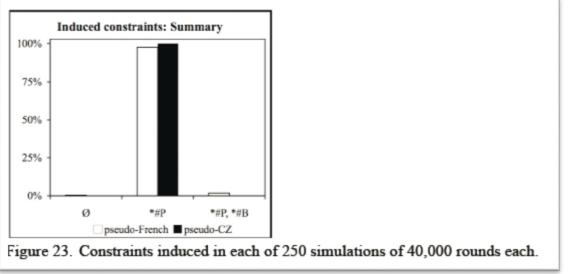
- Important point about phonologization
  - Once \*#P has been promoted high enough, the learner gets no experience of initial [p]!
  - But they do still have one important piece of information listed above—can you guess what?

• The learner's rule for inducing a constraint:

(117) Some segment x is perceptually difficult in some context Context<sub>Z</sub> if either:
a. Accuracy(x/Context<sub>Z</sub>) < threshold</li>
and
Accuracy(x/Context<sub>Z</sub>) < Accuracy(y/Context<sub>Z</sub>) → Constraint \*x/Context<sub>Z</sub>
This difference must be significant (α = 0.01).
b. Accuracy(x/Context<sub>Z</sub>) < FalseAlarm(x/Context<sub>Z</sub>) → Constraint \*x/Context<sub>Z</sub>
(p. 160)

- Where "accuracy" means hit rate
- If there is no hit rate, because the sound never actually occurs in that context, treat it as 0.
- So how would this work for a language with no initial [p]? Let's draw a possible confusion matrix.

• Results: both a learner of simplified French (has initial [p], but it is perceptually difficult) and a learner of simplified Cajonos Zapotec (no initial [p]) learn \*#P in nearly all runs



5

## 4. A selection of other approaches that we won't have time to cover in depth

- <u>Hayes (1999)</u>: as we saw last time, generate lots of features according to a set of templates, and then select the ones that match the phonetic map well, with a bias favoring simpler constraints
- <u>Boersma & Pater (2007)</u>: in Harmonic Grammar, construct *positive* constraints for every property that the observed form has (as well as some other constraints, including negative ones)
- e.g., on observing Canadian English [?ʌɪs] 'ice', construct these, among many others:

(17) Observed structure Constructed constraint

- a. D RAISED DIPHTHONG: A diphthong must be [-low] [-low] (Assign a reward of 1 to each diphthong that is [-low])
- b. D C [-low][-vce] RAISED/VOICELESS: A diphthong preceding a voiceless consonant must be raised (Assign a reward of 1 to each diphthong that is [-low] that precedes a voiceless consonant)

(p. 4)

- <u>Pater (2014)</u> proposes something similar for the same case, but now without positive constraints
- <u>Moreton (2010)</u>: explore infinite space of possible constraints with evolutionary algorithm
  - Every subpart of every possible representation is a constraint
  - Start with a random set of constraints
  - Error-driven: if current grammar selects a candidate that doesn't match the observed true winner...
    - constraints that favor observed forms (correct winners) are allowed to breed.
    - breeding = combine two constraints to produce a new, offspring constraint with aspects of each parent. Offspring can also mutate.
- <u>Pizzo (2013)</u>: Inducing constraints to handle alternations (Turkish vowel harmony and devoicing)
  - On making an error, create a constraint at random
  - According to certain templates
  - Can be faithfulness or markedness
  - Must penalize some way in which the spurious winner differs from the observed winner
  - The researcher can set parameters for how much stem-faithfulness and tier-markedness constraints show be allowed/favored
- <u>Alderete, Tupper & Frisch (2013)</u>: Connectionst model of OCP-Place in Arabic roots

# 5. Coming up next Tuesday (there is no class this Thursday)

• Inducing feature and natural classes

#### References

- Alderete, John, Paul Tupper & Stefan A. Frisch. 2013. Phonological constraint induction in a connectionist network: learning OCP-Place constraints from data. *Language Sciences* 37. 52–69.
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